Incremental, large hollow shaft magnetic

RLI200 (hollow shaft)

Push-pull / RS422



Thanks to its installation depth of min. 10 mm, the bearingless magnetic rotary encoder RLI200, comprising a magnetic ring and sensor head, is ideally suited for plants and machinery where space is very tight. The non-contact measuring principle allows for error-free use even under harsh environmental conditions, as well as ensuring a long service life.

IP68 / IP69k protection, special encapsulation technology and tested resistance to cyclic humidity and damp heat offer the highest levels of reliability, even in exposed outdoor use.

This bearingless encoder can be mounted on shafts with a diameter up to max. 390 mm.











High protection

Reverse polarity

Hard-wearing and robust

- · High shock and vibration resistance.
- · Sturdy housing with IP67 protection. Option: special housing for maximum resistance against condensation (IP68 / IP69k, resistance to cyclic humidity acc. to EN 60068-3-38 as well as damp heat acc. to EN 60068-3-78).
- · Non-contact measuring system, free from wear, ensures a long service life.

Fast start-up

- · Requires very little installation space.
- Large mounting tolerance between magnetic band and sensor head.
- · Slotted hole fixing ensures simple alignment.
- · Function display via LED.

Order code **RLI200**

8.RLI200 |X|X|1|X|X|XXXXX 00

Hub screw

- Magnetic ring mounting method
- 1 = Press fit
- 2 = Hub screw 1)
- 3 = Screwed flange 1)
- **b** Model
- 1 = IP67, standard
- 2 = IP68 / IP69k and humidity tested acc. to EN 60068-3-38, EN 60068-3-78
- Output circuit / Supply voltage
- 1 = RS422 / 4.8 ... 26 V DC
- 2 = Push-pull / 4.8 ... 30 V DC

- Type of connection
- 1 = radial cable, 2 m [6.56'] PUR
- A = radial cable, special length PUR *)
- Available special lengths 2) (connection type A): 3, 5, 8, 10, 15, 20 m [9.84, 16.40, 26.25, 32.80, 49.21, 65.62'] order code expansion .XXXX = length in dm ex.: 8.RLI200.1111A.07000.0760.0030 (for cable length 3 m)
- Pulses per revolution 700, 2240, 2800, 7000 (for hollow shaft ø 76 mm) 1600, 5120, 6400, 16000 (for hollow shaft ø 180 mm) (e.g.: 1600 pulses => 01600)

Hollow shaft diameter 0760 = 76 mm [2.99"] 3) 1800 = 180 mm [7.09"] 3)

Optional on request

- other pulse rates
- other hollow shaft diameter (up to max. 390 mm)

Press fit



- Cable lengths >10 m only possible with supply voltage >10 V.
- 3) With magnetic ring mounting method 2 or 3 on request.







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Accessories / Display type 572		Order no.
Position display, 6-digit	with 4 fast switch outputs and serial interface	6.572.0116.D05
	with 4 fast switch outputs and serial interface and scalable analog output	6.572.0116.D95
Position display, 8-digit	with 4 fast switch outputs and serial interface	6.572.0118.D05
	with 4 fast switch outputs and serial interface and scalable analog output	6.572.0118.D95

Further Kübler accessories can be found at: kuebler.com/accessories Further Kübler cables and connectors can be found at: kuebler.com/connection-technology

Technical data

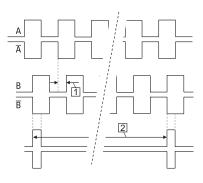
Mechanical characteristics					
Maximum speed		12000 min ⁻¹			
Protection	Model 1 Model 2	IP67 acc. to EN 60529 IP68 / IP69k acc. to EN 60529, DIN 40050-9 and humidity tested			
		acc. to EN 60068-3-38, EN 60068-3-78			
Working temperature		-20 °C +80 °C [-4 °F +176 °F]			
Shock resistance		5000 m/s ² , 1 ms			
Vibration resistance		300 m/s ² , 10 2000 Hz			
Pole gap		2 mm from pole to pole			
Housing (sensor h	ead)	aluminum			
Cable		2 m [6.56'] long, PUR 8 x 0.14 mm ² [AWG 26], shielded, may be used in trailing cable installations			
Status LED	green red	pulse-index error; speed too high or magnetic fields too weak			

Approvals	
CE compliant in accordance with EMC Directive RoHS Directive	2014/30/EU 2011/65/EU
UKCA compliant in accordance with EMC Regulations RoHS Regulations	S.I. 2016/1091 S.I. 2012/3032

Electrical characteristics	S						
Output circuit	RS422		Push-pul	Push-pull			
Supply voltage	4.8 26	VDC	4.8 30 \	4.8 30 VDC			
Power consumption (no load)	typ. 25 n max. 60		,,	typ. 25 mA max. 60 mA			
Permissible load / channel	120 Ohm	120 Ohm		+/- 20 mA			
Min. pulse edge interval	1 μs		1 µs				
Signal level HIGH LOW	min. 2.5 V max. 0.5 V			min. +V - 2.0 V max. 0.5 V			
Reference signal	index periodical 1)						
System accuracy	typ. 0.3° with shaft tolerance g6						
Pulse rate [ppr] 2)	700	2240	2800	7000			
max. speed min ⁻¹	12000	6600	5300	2100			
	1600	5120	6400	16000			
max. speed min ⁻¹	9300	2900	2300	900			

Signal figures

- 1 Pulse edge interval: Pay attention to the instructions in the technical data
- 2 Periodic index signal every 2 mm [0.08"]; the logical assignment A, B and O-signal can change



At every pole change. The signal is generated by the sensor.
 With an input frequency of the evaluation unit of 250 kHz.



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Terminal assignment

	Output circuit	Type of connection	Cable (isolate unused cores individually before initial start-up)									
	1 2	1 1	Signal:	0 V	+V	Α	Ā	В	B	0	0	Ť
	1, 2	1, A	Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield ¹⁾

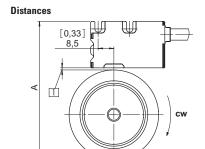
+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V) A, \overline{A} : Incremental output channel A / cosine signal B, \overline{B} : Incremental output channel B / sine signal

0, 0: Reference signal

±: Plug connector housing (shield)

Mounting orientation and permissible mounting tolerances

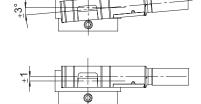


① Distance sensor head / magnetic ring: 0.1 ... 1.0 (0.4 [0.02] recommended)

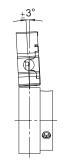
Pulse rate	for distance sensor head / magnetic ring = 0.4 mm [0.02]
700, 2240, 2800, 7000	112.5 [4.43]
1600, 5120, 6400, 16000	227.7 [8.96]



Offset



Tilting



Warning: When mounting the sensor head, please ensure its correct orientation to the magnetic ring!

¹⁾ Shield is attached to connector housing.



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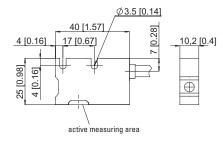
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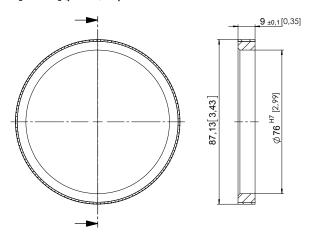
Dimensions

Dimensions in mm [inch]

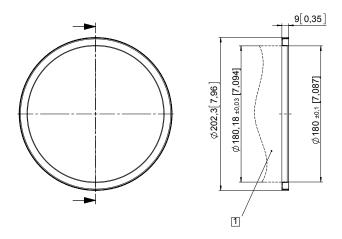
Sensor head



Magnetic ring (press fit) for pulse rate 700, 2240, 2800, 7000



Magnetic ring (press fit) for pulse rate 1600, 5120, 6400, 16000



1 Customer shaft